

# Mathematical methods for modeling and control of open quantum systems<sup>1</sup>

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<sup>1</sup>Lecture-notes, slides and Matlab simulation scripts available at:  
<http://cas.ensmp.fr/~rouchon/LIASFMA/index.html>

<sup>2</sup>Inria-Paris

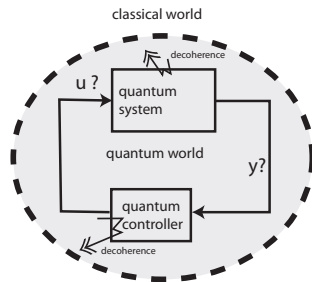
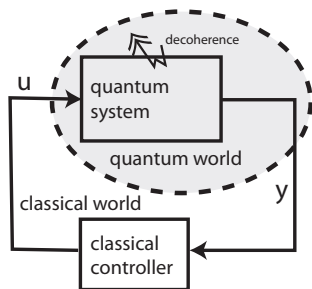
<sup>3</sup>Mines Paris

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- 1 Two kinds of feedback
- 2 Damped harmonic oscillator (low-Q mode)
  - Classical low-Q mode
  - Quantum low-Q mode
  - Wigner representation
- 3 Dynamical model reduction and adiabatic elimination
  - Model reduction and geometric singular perturbations
  - Adiabatic elimination for bipartite quantum systems
- 4 Super-conducting circuit stabilizing a cat-qubit
  - First order RWA
  - Adiabatic elimination of the low-Q mode
  - Numerical simulations
- 5 Conclusion of these lectures

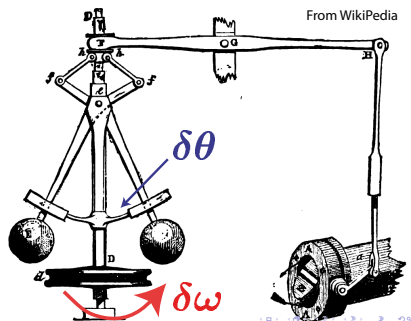
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# Two kinds of quantum feedback



**Measurement-based feedback: controller is classical;** measurement back-action on the quantum system of Hilbert space  $\mathcal{H}$  is stochastic (**collapse of the wave-packet**); the measured output  $y$  is a classical signal; the control input  $u$  is a classical variable appearing in some controlled Schrödinger equation;  $u(t)$  depends on the past measurements  $y(\tau)$ ,  $\tau \leq t$ .

**Coherent/autonomous feedback and reservoir engineering:** the **system of Hilbert space  $\mathcal{H}$**  is coupled to **the controller, another quantum system**; the composite system of Hilbert space  $\mathcal{H}_{\text{controller}} \otimes \mathcal{H}$ , is an open-quantum system relaxing to some target (separable) state. Origin of such relaxation behaviors in open quantum systems: optical pumping of Alfred Kastler, physics Nobel prize 1966.



Third order system

The first variations of speed  $\delta\omega$  and governor angle  $\delta\theta$  obey to

$$\frac{d}{dt}\delta\omega = -a\delta\theta$$

$$\frac{d^2}{dt^2}\delta\theta = -\Lambda\frac{d}{dt}\delta\theta - \Omega^2(\delta\theta - b\delta\omega)$$

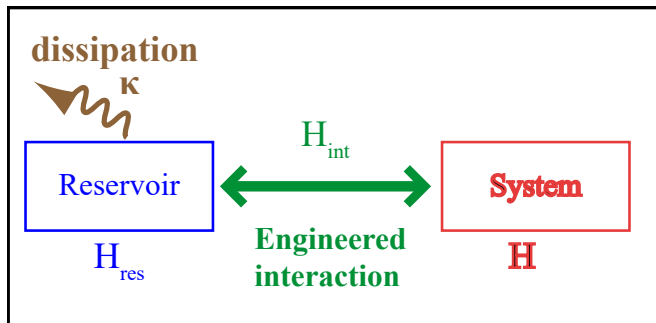
with  $(a, b, \Lambda, \Omega)$  positive parameters.

$$\frac{d^3}{dt^3}\delta\omega + \Lambda\frac{d^2}{dt^2}\delta\omega + \Omega^2\frac{d}{dt}\delta\omega + ab\Omega^2\delta\omega = 0.$$

Characteristic polynomial  $P(s) = s^3 + \Lambda s^2 + \Omega^2 s + ab\Omega^2$  with roots having negative real parts iff  $\Lambda > ab$ : **governor damping must be strong enough to ensure asymptotic stability.**

**Key issues:** asymptotic stability and convergence rates.

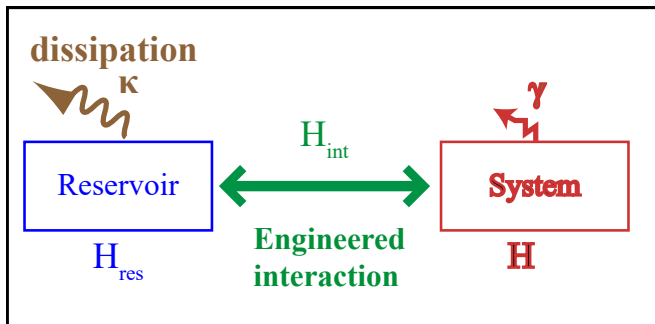
<sup>5</sup>J.C. Maxwell: On governors. Proc. of the Royal Society, No.100, 1868.



$$H = H_{\text{res}} + H_{\text{int}} + H$$

If  $\rho \xrightarrow[t \rightarrow \infty]{} \rho_{\text{res}} \otimes |\bar{\psi}\rangle\langle\bar{\psi}|$  exponentially on a time scale of  $\tau > 0$   
 then .....

<sup>6</sup>See, e.g., the lectures of H. Mabuchi delivered at the "Ecole de physique des Houches", July 2011.



$$H = H_{\text{res}} + H_{\text{int}} + H$$

.....  $\rho \xrightarrow{t \rightarrow \infty} \rho_{\text{res}} \otimes |\bar{\psi}\rangle\langle\bar{\psi}| + \bar{\delta\rho}$ , if  $\tau\gamma \ll 1$  then  $|\bar{\delta\rho}| \ll 1$

Continuous-time models: Lindblad master eq. (quantum Fokker-Planck eq.):

$$\frac{d}{dt}\rho = -\mathcal{A}(\rho) \triangleq -\frac{i}{\hbar}[\mathbf{H}, \rho] + \sum_{\nu} \left( \mathbf{L}_{\nu}\rho\mathbf{L}_{\nu}^{\dagger} - (\mathbf{L}_{\nu}^{\dagger}\mathbf{L}_{\nu}\rho + \rho\mathbf{L}_{\nu}^{\dagger}\mathbf{L}_{\nu})/2 \right),$$

of state  $\rho$  a density operator (Hermitian, non negative, trace-class, trace one) with  $\mathbf{H}$  Hermitian operator and  $\mathbf{L}_{\nu}$  arbitrary operators (usually unbounded).

When  $\mathcal{H}$  is of finite dimension,  $(e^{-t\mathcal{A}})_{t \geq 0}$  is a contraction semi-group for many metrics ( $\text{Tr}(|\rho - \sigma|)$ ,  $\text{Tr}(\sqrt{\sqrt{\rho}\sigma\sqrt{\rho}})$ , see the work of D. Petz).

**Open issues** motivated by **robust** quantum information processing:

- 1 **characterization of the  $\Omega$ -limit support of  $\rho$** : decoherence free spaces are affine spaces where the dynamics are of Schrödinger types; they can be reduced to a point (**pointer-state**);
- 2 **Estimation of convergence rate and robustness.**
- 3 **Reservoir engineering**: design of realistic  $H$  and  $L_{\nu}$  to achieve rapid convergence towards prescribed affine spaces (protection against decoherence).

**Lecture goal: cat-qubits** and autonomous QEC of bit-flips<sup>7</sup>

<sup>7</sup>R. Lescanne, ..., M. Mirrahimi, M. and Z. Leghtas: Exponential suppression of bit-flips in a qubit encoded in an oscillator. 2020, Nat. Phys., Vol. 16, p. 509-513.



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# The driven and damped classical oscillator

Dynamics in the  $(x', p')$  phase plane with  $\omega \gg \kappa$ ,  $\sqrt{u_1^2 + u_2^2}$ :

$$\frac{d}{dt}x' = \omega p', \quad \frac{d}{dt}p' = -\omega x' - \kappa p' - 2u_1 \sin(\omega t) + 2u_2 \cos(\omega t)$$

Define the frame rotating at  $\omega$  by  $(x', p') \mapsto (x, p)$  with

$$x' = \cos(\omega t)x + \sin(\omega t)p, \quad p' = -\sin(\omega t)x + \cos(\omega t)p.$$

Removing highly oscillating terms (rotating wave approximation), from

$$\begin{aligned} \frac{d}{dt}x &= -\kappa \sin^2(\omega t)x + 2u_1 \sin^2(\omega t) + (\kappa p - 2u_2) \sin(\omega t) \cos(\omega t) \\ \frac{d}{dt}p &= -\kappa \cos^2(\omega t)p + 2u_2 \cos^2(\omega t) + (\kappa x - 2u_1) \sin(\omega t) \cos(\omega t) \end{aligned}$$

we get, with  $\alpha = x + ip$  and  $u = u_1 + iu_2$ :

$$\frac{d}{dt}\alpha = -\frac{\kappa}{2}\alpha + u.$$

With  $x' + ip' = \alpha' = e^{-i\omega t}\alpha$ , we have  $\frac{d}{dt}\alpha' = -(\frac{\kappa}{2} + i\omega)\alpha' + ue^{-i\omega t}$

- The Lindblad master equation (quantum analogue of  $\frac{d}{dt}\alpha = -\frac{\kappa}{2}\alpha + u$  with  $\alpha = \text{Tr}(\mathbf{a}\rho)$ ):

$$\frac{d}{dt}\rho = [u\mathbf{a}^\dagger - u^*\mathbf{a}, \rho] + \kappa \left( \mathbf{a}\rho\mathbf{a}^\dagger - \frac{1}{2}\mathbf{a}^\dagger\mathbf{a}\rho - \frac{1}{2}\rho\mathbf{a}^\dagger\mathbf{a} \right).$$

- Consider  $\rho = \mathbf{D}_{\bar{\alpha}}\xi\mathbf{D}_{-\bar{\alpha}}$  with  $\bar{\alpha} = 2u/\kappa$  and  $\mathbf{D}_{\bar{\alpha}} = e^{\bar{\alpha}\mathbf{a}^\dagger - \bar{\alpha}^*\mathbf{a}}$ . We get

$$\frac{d}{dt}\xi = \kappa \left( \mathbf{a}\xi\mathbf{a}^\dagger - \frac{1}{2}\mathbf{a}^\dagger\mathbf{a}\xi - \frac{1}{2}\xi\mathbf{a}^\dagger\mathbf{a} \right)$$

since  $\mathbf{D}_{-\bar{\alpha}}\mathbf{a}\mathbf{D}_{\bar{\alpha}} = \mathbf{a} + \bar{\alpha}$ .

- Informal convergence proof with the strict Lyapunov function  $V(\xi) = \text{Tr}(\xi\mathbf{N})$ :

$$\frac{d}{dt}V(\xi) = -\kappa V(\xi) \Rightarrow V(\xi(t)) = V(\xi_0)e^{-\kappa t}.$$

Since  $\xi(t)$  is Hermitian and non-negative,  $\xi(t)$  tends to  $|0\rangle\langle 0|$  when  $t \mapsto +\infty$ .

## Theorem

Consider with  $u \in \mathbb{C}$ ,  $\kappa > 0$ , the following Cauchy problem

$$\frac{d}{dt}\rho = [u\mathbf{a}^\dagger - u^*\mathbf{a}, \rho] + \kappa (\mathbf{a}\rho\mathbf{a}^\dagger - \frac{1}{2}\mathbf{a}^\dagger\mathbf{a}\rho - \frac{1}{2}\rho\mathbf{a}^\dagger\mathbf{a}), \quad \rho(0) = \rho_0.$$

Assume that the initial state  $\rho_0$  is a density operator with finite energy  $\text{Tr}(\rho_0\mathbf{N}) < +\infty$ . Then exists a unique solution to the Cauchy problem in the Banach space  $\mathcal{K}^1(\mathcal{H})$ , the set of trace class operators on  $\mathcal{H}$ . It is defined for all  $t > 0$  with  $\rho(t)$  a density operator (Hermitian, non-negative and trace-class) that remains in the domain of the Lindblad super-operator

$$\rho \mapsto [u\mathbf{a}^\dagger - u^*\mathbf{a}, \rho] + \kappa (\mathbf{a}\rho\mathbf{a}^\dagger - \frac{1}{2}\mathbf{a}^\dagger\mathbf{a}\rho - \frac{1}{2}\rho\mathbf{a}^\dagger\mathbf{a}).$$

This means that  $t \mapsto \rho(t)$  is differentiable in the Banach space  $\mathcal{K}^1(\mathcal{H})$ . Moreover  $\rho(t)$  converges for the trace-norm towards  $|\bar{\alpha}\rangle\langle\bar{\alpha}|$  when  $t$  tends to  $+\infty$ , where  $|\bar{\alpha}\rangle$  is the coherent state of complex amplitude  $\bar{\alpha} = \frac{2u}{\kappa}$ .

## Lemma

Consider with  $u \in \mathbb{C}$ ,  $\kappa > 0$ , the following Cauchy problem

$$\frac{d}{dt}\rho = [u\mathbf{a}^\dagger - u^*\mathbf{a}, \rho] + \kappa (\mathbf{a}\rho\mathbf{a}^\dagger - \frac{1}{2}\mathbf{a}^\dagger\mathbf{a}\rho - \frac{1}{2}\rho\mathbf{a}^\dagger\mathbf{a}), \quad \rho(0) = \rho_0.$$

- 1 for any initial density operator  $\rho_0$  with  $\text{Tr}(\rho_0\mathbf{N}) < +\infty$ , we have  $\frac{d}{dt}\alpha = -\frac{\kappa}{2}(\alpha - \bar{\alpha})$  where  $\alpha = \text{Tr}(\rho\mathbf{a})$  and  $\bar{\alpha} = \frac{2u}{\kappa}$ .
- 2 Assume that  $\rho_0 = |\beta_0\rangle\langle\beta_0|$  where  $\beta_0$  is some complex amplitude. Then for all  $t \geq 0$ ,  $\rho(t) = |\beta(t)\rangle\langle\beta(t)|$  remains a coherent state of amplitude  $\beta(t)$  solution of the following equation:  
 $\frac{d}{dt}\beta = -\frac{\kappa}{2}(\beta - \bar{\alpha})$  with  $\beta(0) = \beta_0$ .

Statement 2 relies on:

$$\mathbf{a}|\beta\rangle = \beta|\beta\rangle, \quad |\beta\rangle = e^{-\frac{\beta\beta^*}{2}} e^{\beta\mathbf{a}^\dagger} |0\rangle \quad \frac{d}{dt}|\beta\rangle = \left(-\frac{1}{2}(\beta^*\dot{\beta} + \beta\dot{\beta}^*) + \dot{\beta}\mathbf{a}^\dagger\right) |\beta\rangle.$$

Parameters  $\omega \gg \kappa$ ,  $|u|$  and  $n_{\text{th}} \geq 0$ :

$$\begin{aligned} \frac{d}{dt} \rho = [ua^\dagger - u^* a, \rho] + (1 + n_{\text{th}}) \kappa \left( a \rho a^\dagger - \frac{1}{2} a^\dagger a \rho - \frac{1}{2} \rho a^\dagger a \right) \\ + n_{\text{th}} \kappa \left( a^\dagger \rho a - \frac{1}{2} a a^\dagger \rho - \frac{1}{2} \rho a a^\dagger \right). \end{aligned}$$

**Key issue:**  $\lim_{t \rightarrow +\infty} \rho(t) = ?$ .

The passage to **another representation** via the Wigner function:

- Since  $\mathbf{D}_\alpha e^{i\pi N} \mathbf{D}_{-\alpha}$  bounded and Hermitian operator (the dual of  $\mathcal{K}^1(\mathcal{H})$  is  $\mathcal{B}(\mathcal{H})$ ),

$$W^{\{\rho\}}(x, p) = \frac{2}{\pi} \text{Tr} \left( \rho \mathbf{D}_\alpha e^{i\pi N} \mathbf{D}_{-\alpha} \right) \quad \text{with} \quad \alpha = x + ip \in \mathbb{C},$$

defines a real and bounded function  $|W^{\{\rho\}}(x, p)| \leq \frac{2}{\pi}$ .

- For a coherent state  $\rho = |\beta\rangle\langle\beta|$  with  $\beta \in \mathbb{C}$ :

$$W^{\{|\beta\rangle\langle\beta|\}}(x, p) = \frac{2}{\pi} e^{-2|\beta - (x+ip)|^2}.$$

# The partial differential equation satisfied by the Wigner function (1)<sup>8</sup>

With  $\mathbf{D}_\alpha = e^{\alpha \mathbf{a}^\dagger} e^{-\alpha^* \mathbf{a}} e^{-\alpha \alpha^* / 2} = e^{-\alpha^* \mathbf{a}} e^{\alpha \mathbf{a}^\dagger} e^{\alpha \alpha^* / 2}$  we have:

$$\frac{\pi}{2} W^{\{\rho\}}(\alpha, \alpha^*) = \text{Tr} \left( \rho e^{\alpha \mathbf{a}^\dagger} e^{-\alpha^* \mathbf{a}} e^{i\pi \mathbf{N}} e^{\alpha^* \mathbf{a}} e^{-\alpha \mathbf{a}^\dagger} \right)$$

where  $\alpha$  and  $\alpha^*$  are seen as independent variables:

$$\frac{\partial}{\partial \alpha} = \frac{1}{2} \left( \frac{\partial}{\partial X} - i \frac{\partial}{\partial p} \right), \quad \frac{\partial}{\partial \alpha^*} = \frac{1}{2} \left( \frac{\partial}{\partial X} + i \frac{\partial}{\partial p} \right)$$

We have  $\frac{\pi}{2} \frac{\partial}{\partial \alpha} W^{\{\rho\}}(\alpha, \alpha^*) = \text{Tr} \left( (\rho \mathbf{a}^\dagger - \mathbf{a}^\dagger \rho) \mathbf{D}_\alpha e^{i\pi \mathbf{N}} \mathbf{D}_{-\alpha} \right)$  Since  $\mathbf{a}^\dagger \mathbf{D}_\alpha e^{i\pi \mathbf{N}} \mathbf{D}_{-\alpha} = \mathbf{D}_\alpha e^{i\pi \mathbf{N}} \mathbf{D}_{-\alpha} (2\alpha^* - \mathbf{a}^\dagger)$ , we get

$$\frac{\partial}{\partial \alpha} W^{\{\rho\}}(\alpha, \alpha^*) = 2\alpha^* W^{\{\rho\}}(\alpha, \alpha^*) - 2W^{\{\mathbf{a}^\dagger \rho\}}(\alpha, \alpha^*).$$

Thus  $W^{\{\mathbf{a}^\dagger \rho\}}(\alpha, \alpha^*) = \alpha^* W^{\{\rho\}}(\alpha, \alpha^*) - \frac{1}{2} \frac{\partial}{\partial \alpha} W^{\{\rho\}}(\alpha, \alpha^*)$ , i.e.

$$W^{\{\mathbf{a}^\dagger \rho\}} = \left( \alpha^* - \frac{1}{2} \frac{\partial}{\partial \alpha} \right) W^{\{\rho\}}.$$

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<sup>8</sup>See the excellent Wikipedia article:

# The partial differential equation satisfied by the Wigner function (2)

Similar computations yield to the following correspondence rules:

$$\begin{aligned}W^{\{\rho\mathbf{a}\}} &= \left(\alpha - \frac{1}{2}\frac{\partial}{\partial\alpha^*}\right)W^{\{\rho\}}, & W^{\{\mathbf{a}\rho\}} &= \left(\alpha + \frac{1}{2}\frac{\partial}{\partial\alpha^*}\right)W^{\{\rho\}} \\W^{\{\rho\mathbf{a}^\dagger\}} &= \left(\alpha^* + \frac{1}{2}\frac{\partial}{\partial\alpha}\right)W^{\{\rho\}}, & W^{\{\mathbf{a}^\dagger\rho\}} &= \left(\alpha^* - \frac{1}{2}\frac{\partial}{\partial\alpha}\right)W^{\{\rho\}}.\end{aligned}$$

Thus

$$\begin{aligned}\frac{d}{dt}\rho &= [u\mathbf{a}^\dagger - u^*\mathbf{a}, \rho] + (1 + n_{\text{th}})\kappa \left(\mathbf{a}\rho\mathbf{a}^\dagger - \frac{1}{2}\mathbf{a}^\dagger\mathbf{a}\rho - \frac{1}{2}\rho\mathbf{a}^\dagger\mathbf{a}\right) \\ &\quad + n_{\text{th}}\kappa \left(\mathbf{a}^\dagger\rho\mathbf{a} - \frac{1}{2}\mathbf{a}\mathbf{a}^\dagger\rho - \frac{1}{2}\rho\mathbf{a}\mathbf{a}^\dagger\right).\end{aligned}$$

becomes

$$\frac{\partial}{\partial t}W^{\{\rho\}} = \frac{\kappa}{2} \left( \frac{\partial}{\partial\alpha}(\alpha - \bar{\alpha}) + \frac{\partial}{\partial\alpha^*}(\alpha^* - \bar{\alpha}^*) + (1 + 2n_{\text{th}})\frac{\partial^2}{\partial\alpha\partial\alpha^*} \right) W^{\{\rho\}}$$



Since the Green function of

$$\begin{aligned} \frac{\partial}{\partial t} W^{\{\rho\}} = & \frac{\kappa}{2} \left( \frac{\partial}{\partial x} \left( (x - \bar{x}) W^{\{\rho\}} \right) + \frac{\partial}{\partial p} \left( (p - \bar{p}) W^{\{\rho\}} \right) \right. \\ & \left. + \frac{1+2n_{\text{th}}}{4} \left( \frac{\partial^2 W^{\{\rho\}}}{\partial x^2} + \frac{\partial^2 W^{\{\rho\}}}{\partial p^2} \right) \right) \end{aligned}$$

is the following time-varying Gaussian function

$$G(x, p, t, x_0, p_0) = \frac{\exp \left( - \frac{\left( x - \bar{x} - (x_0 - \bar{x}) e^{-\frac{\kappa t}{2}} \right)^2 + \left( p - \bar{p} - (p_0 - \bar{p}) e^{-\frac{\kappa t}{2}} \right)^2}{(n_{\text{th}} + \frac{1}{2})(1 - e^{-\kappa t})} \right)}{\pi (n_{\text{th}} + \frac{1}{2})(1 - e^{-\kappa t})}$$

we can compute  $W_t^{\{\rho\}}$  from  $W_0^{\{\rho\}}$  for all  $t > 0$ :

$$W_t^{\{\rho\}}(x, p) = \int_{\mathbb{R}^2} W_0^{\{\rho\}}(x', p') G(x, p, t, x', p') dx' dp'$$

Combining

- $W_t^{\{\rho\}}(x, p) = \int_{\mathbb{R}^2} W_0^{\{\rho\}}(x', p') G(x, p, t, x', p') dx' dp'$ .

- $G$  uniformly bounded and

$$\lim_{t \rightarrow +\infty} G(x, p, t, x', p') = \frac{1}{\pi(n_{\text{th}} + \frac{1}{2})} \exp\left(-\frac{(x-\bar{x})^2 + (p-\bar{p})^2}{(n_{\text{th}} + \frac{1}{2})}\right)$$

- $W_0^{\{\rho\}}$  in  $L^1$  with  $\iint_{\mathbb{R}^2} W_0^{\{\rho\}} = 1$

- dominate convergence theorem

shows that all the solutions converge to a unique steady-state Gaussian density function, centered in  $(\bar{x}, \bar{p})$  with variance  $\frac{1}{2} + n_{\text{th}}$ :

$$\forall (x, p) \in \mathbb{R}^2, \quad \lim_{t \rightarrow +\infty} W_t^{\{\rho\}}(x, p) = \frac{1}{\pi(n_{\text{th}} + \frac{1}{2})} \exp\left(-\frac{(x - \bar{x})^2 + (p - \bar{p})^2}{(n_{\text{th}} + \frac{1}{2})}\right).$$

## Diffusion along $x$ and $p$ of Wigner function $W^\rho(x, p)$

With correspondence rules:

$$W^{\{\rho a\}} = \left( \alpha - \frac{1}{2} \frac{\partial}{\partial \alpha^*} \right) W^{\{\rho\}}, \quad W^{\{a \rho\}} = \left( \alpha + \frac{1}{2} \frac{\partial}{\partial \alpha^*} \right) W^{\{\rho\}}$$
$$W^{\{\rho a^\dagger\}} = \left( \alpha^* + \frac{1}{2} \frac{\partial}{\partial \alpha} \right) W^{\{\rho\}}, \quad W^{\{a^\dagger \rho\}} = \left( \alpha^* - \frac{1}{2} \frac{\partial}{\partial \alpha} \right) W^{\{\rho\}}$$

the super-operator

$$\rho \mapsto (\mathbf{a} + \mathbf{a}^\dagger)\rho(\mathbf{a} + \mathbf{a}^\dagger) - \frac{1}{2}((\mathbf{a} + \mathbf{a}^\dagger)^2\rho + \rho(\mathbf{a} + \mathbf{a}^\dagger)^2)$$

becomes in Wigner representation<sup>9</sup>

$$W^{\{\rho\}} \mapsto \frac{-1}{2} \left( \frac{\partial}{\partial \alpha} - \frac{\partial}{\partial \alpha^*} \right)^2 W^{\{\rho\}}(\alpha, \alpha^*) \equiv \frac{1}{2} \frac{\partial^2}{\partial p^2} W^{\{\rho\}}(x, p).$$


Similarly, the super-operator

$$\rho \mapsto (\mathbf{a} - \mathbf{a}^\dagger)\rho(\mathbf{a} - \mathbf{a}^\dagger) - \frac{1}{2}((\mathbf{a} - \mathbf{a}^\dagger)^2\rho + \rho(\mathbf{a} - \mathbf{a}^\dagger)^2)$$

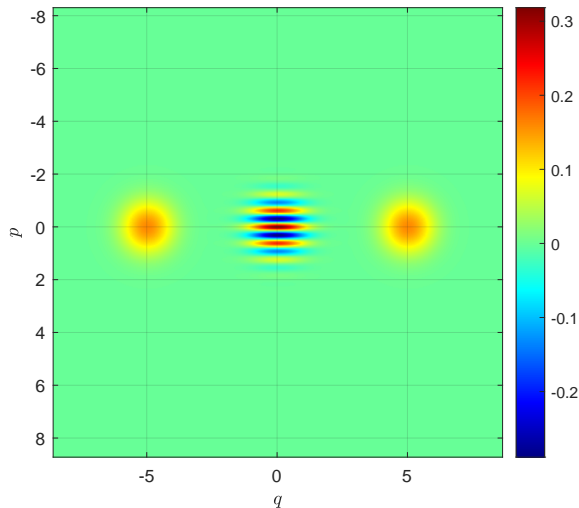
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<sup>9</sup>Use the fact that  $\frac{\partial}{\partial \alpha} = \frac{1}{2} \left( \frac{\partial}{\partial x} - i \frac{\partial}{\partial p} \right)$ ,  $\frac{\partial}{\partial \alpha^*} = \frac{1}{2} \left( \frac{\partial}{\partial x} + i \frac{\partial}{\partial p} \right)$  and  $\alpha = x + ip$ . 

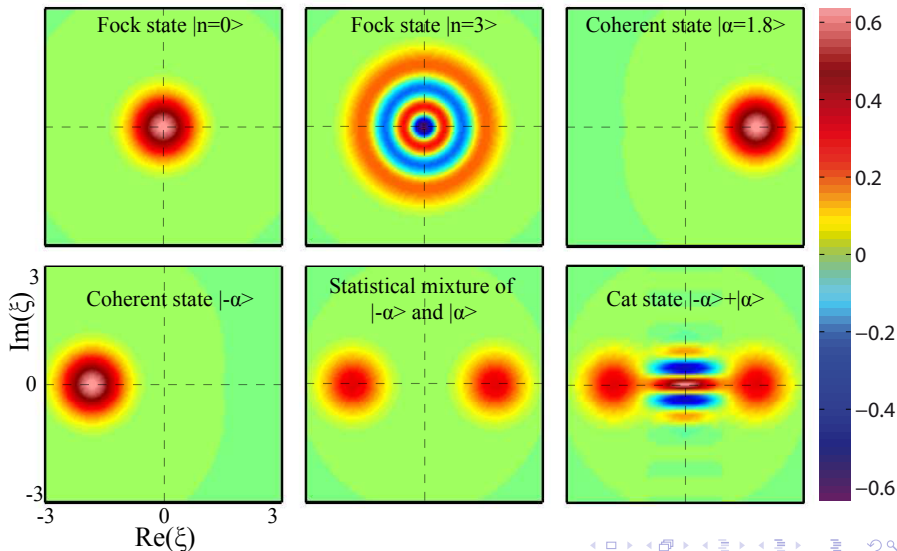
# Wigner function<sup>10</sup> of $|\alpha\rangle + |-\alpha\rangle$ ("Schrödinger cat" with $\alpha = 5$ )



<sup>10</sup>For  $\psi \in L^2(\mathbb{R}, \mathbb{C})$ :  $W(q, p) = \frac{1}{\pi} \int_{-\infty}^{+\infty} \psi^*(q - \frac{u}{2}) \psi(q + \frac{u}{2}) e^{-2ipu} du$ .

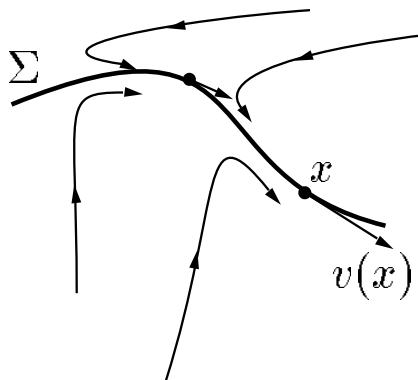
# Wigner function $W^\rho$ for different values of the density operator $\rho$

$$W^\rho : \mathbb{C} \ni \xi \rightarrow \frac{2}{\pi} \text{Tr} \left( \left( \mathbf{D}_\xi e^{i\pi \mathbf{N}} \mathbf{D}_\xi^\dagger \right) \rho \right) \in [-2/\pi, 2/\pi]$$



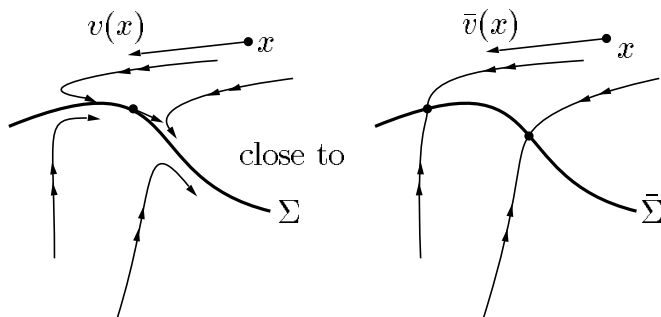
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What is a dynamical reduced model for  $\frac{d}{dt}x = v(x)$  ?



A possible answer:

restriction to an attractive invariant manifold  $\Sigma$ .

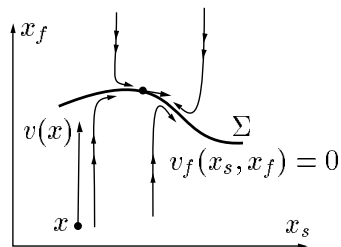


Geometric definition independent of coordinates due to Fenichel<sup>11</sup>:

- $x \mapsto v(x)$  close to  $x \mapsto \bar{v}(x)$ .
- $\bar{v}(x) = 0$  define a manifold  $\bar{\Sigma}$  of dimension  $n_s < n = \dim(x)$  of steady-states for  $\bar{v}(x)$ .
- $n_f = n - n_s$  eigenvalues of  $\left. \frac{\partial \bar{v}}{\partial x} \right|_{\bar{\Sigma}}$  are stable (negative real parts).

<sup>11</sup>N. Fenichel: Geometric singular perturbation theory for ordinary differential equations. J. Diff. Equations, 1979, 31, 53-98.





Any slow/fast system, can be put, after a suitable change of coordinates, in to a **quasi-vertical vector field**  $v$ :

$$\begin{aligned} \frac{d}{dt}x_s &= v_s(x_s, x_f) = \epsilon \tilde{v}_s(x_s, x_f, \epsilon) \\ \frac{d}{dt}x_f &= v_f(x_s, x_f) \end{aligned}$$

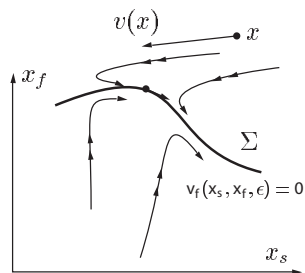
with  $0 < \epsilon \ll 1$ .

The reduced system  $\frac{d}{dt}x_s = v_s(x_s, x_f)$  with  $0 = v_f(x_s, x_f)$  is correct if  $\frac{d}{dt}\xi_f = v_f(x_s, \xi_f)$  hyperbolically stable for any fixed  $x_s$ .

In general, modeling variables  $x$  are **not** Tikhonov variables.

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<sup>12</sup>See, e.g., F. Verhulst: Methods and Applications of Singular Perturbations: Boundary Layers and Multiple Timescale Dynamics. Springer, 2005



Example with the heuristic method:

$$\frac{d}{dt}x_s = 2(x_f - x_s) + \epsilon x_f \quad \frac{d}{dt}x_f = x_s - x_f$$

- 1- compute  $x_f$  versus  $x_s$  from  $\frac{d}{dt}x_f = 0$ ;
- 2- plug  $x_f = x_s$  into  $\frac{d}{dt}x_s$  to obtain

$$\frac{d}{dt}x_s = \epsilon x_s \quad (\text{wrong slow model !})$$

The reduced model of  $\frac{d}{dt}x_s = v_s(x_s, x_f, \epsilon)$ ,  $\frac{d}{dt}x_f = v_f(x_s, x_f, \epsilon)$  is<sup>13</sup>

$$\frac{d}{dt}x_s = \left( 1 + \frac{\partial v_s}{\partial x_f} \left( \frac{\partial v_f}{\partial x_f} \right)^{-2} \frac{\partial v_f}{\partial x_s} \right)^{-1} v_s(x_s, x_f, \epsilon) + O(\epsilon^2), \quad v_f(x_s, x_f, \epsilon) = 0.$$

Same example with the correct method: with  $\frac{\partial v_s}{\partial x_f} = 2$ ,  $\frac{\partial v_f}{\partial x_s} = 1 = -\frac{\partial v_f}{\partial x_f}$ , we get the correct slow model,  $\frac{d}{dt}x_s = \epsilon x_s / 3$ .

<sup>13</sup>J. Carr: Application of Center Manifold Theory. Springer, 1981.

# Slow/fast composite quantum systems

Take  $0 < \epsilon \ll 1$  and composite system made of subsystem  $A$  with Hilbert space  $\mathcal{H}_A$  and subsystem  $B$  with Hilbert space  $\mathcal{H}_B$ :

$$\frac{d}{dt}\rho = \mathcal{L}_B(\rho) + \epsilon \left( -i[\mathbf{H}_{\text{int}}, \rho] + \mathcal{L}_A(\rho) \right)$$

where

- $\mathcal{L}_B(\rho)$  is a Lindbladian dynamics on  $\mathcal{H}_B$  converging towards a unique steady-state density operator  $\bar{\rho}_B$  on  $\mathcal{H}_B$ .
- $\mathcal{L}_A(\rho)$  is a Lindbladian dynamics on  $\mathcal{H}_A$
- $AB$ -interaction Hamiltonian  $\mathbf{H}_{\text{int}} = \sum_{k=1}^m \mathbf{A}_k \otimes \mathbf{B}_k$ , with  $\mathbf{A}_k$  and  $\mathbf{B}_k$  Hermitian operators on  $\mathcal{H}_A$  and  $\mathcal{H}_B$  respectively.

When  $\epsilon = 0$ , for all initial state  $\rho_0$  on  $\mathcal{H}_A \otimes \mathcal{H}_B$ , the solution of  $\frac{d}{dt}\rho = \mathcal{L}_B(\rho)$  converges towards the separable steady-state  $\text{Tr}_B(\rho_0) \otimes \bar{\rho}_B$ .

For  $0 < \epsilon \ll 1$ , the attractive steady-state manifold

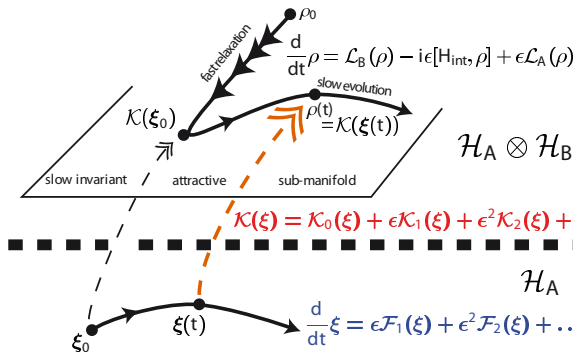
$$\bar{\Sigma} = \left\{ \rho_A \otimes \bar{\rho}_B \mid \rho_A \text{ density operator on } \mathcal{H}_A \right\}$$

becomes  $\Sigma_\epsilon$ , an attractive invariant manifold where the evolution is slow.

$\Sigma_\epsilon$  can be parameterized via density operators  $\xi$  on  $\mathcal{H}_A$  with a slow evolution.

Approximation of such parametrization and slow evolution can be done via asymptotic expansion in  $\epsilon$ . Is-it always possible to preserve positivity of  $\rho$  ?

Always OK for second order expansion.



**Lindbladian slow dynamics** on a density operator  $\xi$  on  $\mathcal{H}_A$ ,

$$\frac{d}{dt} \xi = \epsilon\mathcal{F}_1(\xi) + \epsilon^2\mathcal{F}_2(\xi) + \dots$$

with a **Kraus map** giving density operator  $\rho$  on  $\mathcal{H}_A \otimes \mathcal{H}_B$  from  $\xi$ :

$$\rho = \mathcal{K}(\xi) = \mathcal{K}_0(\xi) + \epsilon\mathcal{K}_1(\xi) + \epsilon^2\mathcal{K}_2(\xi) + \dots$$

<sup>14</sup>Azouit, R. / Chittaro, F. / Sarlette, A. / PR: Towards generic adiabatic elimination for bipartite open quantum systems 2017, Quantum Science and Technology, Vol. 2, p. 044011

# An iterative procedure based on center manifold approximation

Plug

$$\rho = \mathcal{K}(\xi) = \xi \otimes \bar{\rho}_B + \epsilon \mathcal{K}_1(\xi) + \dots, \quad \text{and} \quad \frac{d}{dt} \xi = \mathcal{F}(\xi) = \epsilon \mathcal{F}_1(\xi) + \epsilon^2 \mathcal{F}_2(\xi) + \dots$$

into invariance condition

$$\mathcal{L}_B(\mathcal{K}(\xi)) - \epsilon i[\mathbf{H}_{\text{int}}, \mathcal{K}(\xi)] + \epsilon \mathcal{L}_A(\mathcal{K}(\xi)) = \frac{d}{dt} \rho = \mathcal{K}(\mathcal{F}(\xi))$$

and identify terms of same orders:

$$\text{order 1: } \mathcal{L}_B(\mathcal{K}_1(\xi)) - i[\mathbf{H}_{\text{int}}, \mathcal{K}_0(\xi)] + \mathcal{L}_A(\mathcal{K}_0(\xi)) = \mathcal{K}_0(\mathcal{F}_1(\xi))$$

$$\text{order 2: } \mathcal{L}_B(\mathcal{K}_2(\xi)) - i[\mathbf{H}_{\text{int}}, \mathcal{K}_1(\xi)] + \mathcal{L}_A(\mathcal{K}_1(\xi)) = \mathcal{K}_0(\mathcal{F}_2(\xi)) + \mathcal{K}_1(\mathcal{F}_1(\xi))$$

...

At each order

- 1 take the trace versus  $B$  to get the correction to  $\mathcal{F}$
- 2 compute the correction to  $\mathcal{K}$  via  $-\mathcal{L}_B^{-1}$ , a super operator for zero-trace operators  $\mathbf{W}$  on  $\mathcal{H}_A$

$$-\mathcal{L}_B^{-1}(\mathbf{W}) = \int_0^{+\infty} e^{t\mathcal{L}_B}(\mathbf{W}) dt$$

that coincides with the restriction to zero-trace operators of a completely positive (CP) map.

## Second order approximation when $B$ is a low-Q mode

For  $\mathcal{L}_B(\rho) = \kappa_b \left( \mathbf{b}\rho\mathbf{b}^\dagger - \frac{1}{2}(\mathbf{b}^\dagger\mathbf{b}\rho + \rho\mathbf{b}^\dagger\mathbf{b}) \right)$  one gets using  $\bar{\rho}_B = |0_b\rangle\langle 0_b|$ ,

$$\frac{d}{dt}\xi = -i\epsilon \left[ \sum_k \beta_k \mathbf{A}_k, \xi \right] + \epsilon \mathcal{L}_A(\xi) + \frac{4\epsilon^2}{\kappa_b} \left( \sum_k \mathbf{L}_k \xi \mathbf{L}_k^\dagger - \frac{1}{2} \left( \mathbf{L}_k^\dagger \mathbf{L}_k \xi + \xi \mathbf{L}_k^\dagger \mathbf{L}_k \right) \right) + O(\epsilon^3)$$

with

$$\rho = e^{i\epsilon W_1} (\xi \otimes |0_b\rangle\langle 0_b|) e^{-i\epsilon W_1} + O(\epsilon^2)$$

and where

- $\beta_k = \langle 0_b | \mathbf{B}_k | 0_b \rangle$ ,
- $\mathbf{L}_k = \sum_{k'=1}^m \Lambda_{k,k'} \mathbf{A}_{k'}$  based on Cholesky factorization  $\Lambda^\dagger \Lambda = G$  of the following Gram matrix

$$G_{kk'} = \sum_{n_b=1}^{+\infty} \left( \frac{1}{\sqrt{n_b}} \langle n_b | \mathbf{B}_k | 0_b \rangle \right)^* \left( \frac{1}{\sqrt{n_b}} \langle n_b | \mathbf{B}_{k'} | 0_b \rangle \right).$$

- $\mathbf{W}_1 = \frac{2}{\kappa_b} \sum_{k=1}^m \mathbf{A}_k \otimes \left( (\mathbf{b}^\dagger \mathbf{b})^{-1} \mathbf{B}_k + \mathbf{B}_k (\mathbf{b}^\dagger \mathbf{b})^{-1} \right)$  using  $(\mathbf{b}^\dagger \mathbf{b})^{-1} = \sum_{n_b > 1} \frac{1}{n_b} |n_b\rangle\langle n_b|$ .

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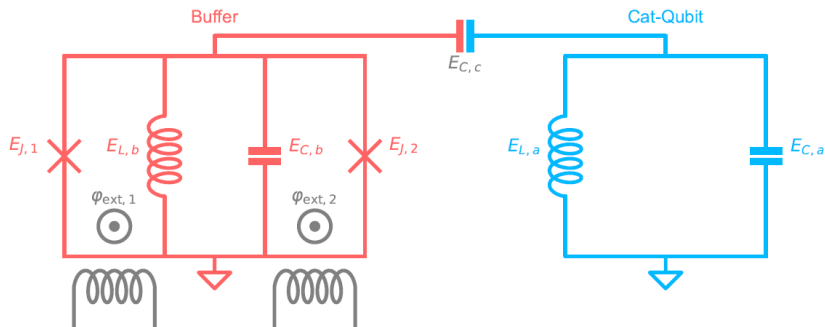


Figure S3. Equivalent circuit diagram. The cat-qubit (blue), a linear resonator, is capacitively coupled to the buffer (red). One recovers the circuit of Fig. 2 by replacing the buffer inductance with a 5-junction array and by setting  $\varphi_{\Sigma} = (\varphi_{\text{ext},1} + \varphi_{\text{ext},2})/2$  and  $\varphi_{\Delta} = (\varphi_{\text{ext},1} - \varphi_{\text{ext},2})/2$ . Not shown here: the buffer is capacitively coupled to a transmission line, the cat-qubit resonator is coupled to a transmon qubit

<sup>15</sup>R. Lescanne, ..., M. Mirrahimi, M. and Z. Leghtas: Exponential suppression of bit-flips in a qubit encoded in an oscillator. 2020, Nat. Phys. , Vol. 16, p. 509-513. See also the patent underlying the startup Alice&Bob.



# Quantum analysis of the circuit stabilizing a cat-qubit (1)

Quantum Hamiltonian: two commuting annihilation operators  $\mathbf{a} = (q_a + \frac{\partial}{\partial q_a})/\sqrt{2}$  and  $\mathbf{b} = (q_b + \frac{\partial}{\partial q_b})/\sqrt{2}$  with  $[\mathbf{a}, \mathbf{a}^\dagger] = I$ ,  $[\mathbf{b}, \mathbf{b}^\dagger] = I$

$$\mathbf{H}_1(t) = \omega_a \mathbf{a}^\dagger \mathbf{a} + \omega_b \mathbf{b}^\dagger \mathbf{b} + 2g \cos(\phi_a(\mathbf{a} + \mathbf{a}^\dagger) + \phi_b(\mathbf{b} + \mathbf{b}^\dagger)) + (2\omega_a - \omega_b)tI$$

**Change of frame** for  $\frac{d}{dt}\rho_1 = -i[\mathbf{H}_1(t), \rho_1]$ : new density operator

$$\rho_2 = \exp(i\omega_a t \mathbf{a}^\dagger \mathbf{a} + i\omega_b t \mathbf{b}^\dagger \mathbf{b}) \rho_1 \exp(-i\omega_a t \mathbf{a}^\dagger \mathbf{a} - i\omega_b t \mathbf{b}^\dagger \mathbf{b})$$

is governed by  $\frac{d}{dt}\rho_2 = -i[\mathbf{H}_2(t), \rho_2]$  with

$$\mathbf{H}_2(t) = g e^{i(2\omega_a - \omega_b)t} \exp(i\phi_a(e^{-i\omega_a t} \mathbf{a} + e^{i\omega_a t} \mathbf{a}^\dagger) + i\phi_b(e^{-i\omega_b t} \mathbf{b} + e^{i\omega_b t} \mathbf{b}^\dagger)) + h.c.$$

Expansion up-to order 3 versus  $\phi_a, \phi_b \ll 1$ :

$$\begin{aligned} \mathbf{H}_2(t) \approx g e^{i(2\omega_a - \omega_b)t} & \left( I + i\phi_a(e^{-i\omega_a t} \mathbf{a} + e^{i\omega_a t} \mathbf{a}^\dagger) - \frac{\phi_a^2}{2}(e^{-i\omega_a t} \mathbf{a} + e^{i\omega_a t} \mathbf{a}^\dagger)^2 - \frac{i\phi_a^3}{6}(e^{-i\omega_a t} \mathbf{a} + e^{i\omega_a t} \mathbf{a}^\dagger)^3 \right) \dots \\ & \left( I + i\phi_b(e^{-i\omega_b t} \mathbf{b} + e^{i\omega_b t} \mathbf{b}^\dagger) - \frac{\phi_b^2}{2}(e^{-i\omega_b t} \mathbf{b} + e^{i\omega_b t} \mathbf{b}^\dagger)^2 - \frac{i\phi_b^3}{6}(e^{-i\omega_b t} \mathbf{b} + e^{i\omega_b t} \mathbf{b}^\dagger)^3 \right) + h.c. \end{aligned}$$

## Quantum analysis of the circuit stabilizing a cat-qubit (2)

$$\begin{aligned} \mathbf{H}_2(t) &\approx g e^{i(2\omega_a - \omega_b)t} \dots \\ &\left( \mathbf{I} + i\phi_a (e^{-i\omega_a t} \mathbf{a} + e^{i\omega_a t} \mathbf{a}^\dagger) - \frac{\phi_a^2}{2} (e^{-i\omega_a t} \mathbf{a} + e^{i\omega_a t} \mathbf{a}^\dagger)^2 - \frac{i\phi_a^3}{6} (e^{-i\omega_a t} \mathbf{a} + e^{i\omega_a t} \mathbf{a}^\dagger)^3 \right) \dots \\ &\left( \mathbf{I} + i\phi_b (e^{-i\omega_b t} \mathbf{b} + e^{i\omega_b t} \mathbf{b}^\dagger) - \frac{\phi_b^2}{2} (e^{-i\omega_b t} \mathbf{b} + e^{i\omega_b t} \mathbf{b}^\dagger)^2 - \frac{i\phi_b^3}{6} (e^{-i\omega_b t} \mathbf{b} + e^{i\omega_b t} \mathbf{b}^\dagger)^3 \right) \\ &\quad + h.c. \end{aligned}$$

When  $\omega_a/\omega_b$  irrational **only two secular terms** (i.e. non-oscillatory):  
–  $ig_2 \mathbf{a}^2 \mathbf{b}^\dagger$  and its Hermitian conjugate  $ig_2 (\mathbf{a}^\dagger)^2 \mathbf{b}$  where  $g_2 = g\phi_a^2\phi_b/2$  (order exceeding 3 in  $\phi_a, \phi_b \ll 1$  are neglected).

Justify the following approximate time-invariant Hamiltonian for  $\mathbf{H}_2$  (**rotating wave approximation**): :

$$\mathbf{H}_2(t) \approx -ig_2 \mathbf{a}^2 \mathbf{b}^\dagger + ig_2 (\mathbf{a}^\dagger)^2 \mathbf{b}.$$

Finer approximations via high-order **averaging** techniques.

Cat-qubit stored in oscillator  $\mathbf{a}$ , **controller based on a damped oscillator  $\mathbf{b}$**  stabilizing against one decoherence channel (bit-flip):

$$\begin{aligned}\frac{d}{dt}\rho &= -[g_2\mathbf{a}^2\mathbf{b}^\dagger - g_2(\mathbf{a}^\dagger)^2\mathbf{b}, \rho] + [u\mathbf{b}^\dagger - u^*\mathbf{b}, \rho] + \kappa_b(\mathbf{b}\rho\mathbf{b}^\dagger - (\mathbf{b}^\dagger\mathbf{b}\rho + \rho\mathbf{b}^\dagger\mathbf{b})/2) \\ &= -[g_2(\mathbf{a}^2 - \alpha^2)\mathbf{b}^\dagger - g_2((\mathbf{a}^\dagger)^2 - (\alpha^2))\mathbf{b}, \rho] + \kappa_b(\mathbf{b}\rho\mathbf{b}^\dagger - (\mathbf{b}^\dagger\mathbf{b}\rho + \rho\mathbf{b}^\dagger\mathbf{b})/2)\end{aligned}$$

with  $\alpha \in \mathbb{C}$  such that  $\alpha^2 = u/g_2$ , the drive amplitude  $u \in \mathbb{C}$  applied to mode  $\mathbf{b}$  and  $1/\kappa_b > 0$  the short life-time of photon in mode  $\mathbf{b}$ .

Any density operator  $\bar{\rho} = \bar{\rho}_a \otimes |0\rangle\langle 0|_b$  **is a steady-state as soon as the support of  $\bar{\rho}_a$  belongs to the two dimensional vector space spanned by the coherent states  $|\alpha\rangle$  and  $|\alpha\rangle$**  ( $\text{range}(\bar{\rho}_a) \subset \text{span}\{|\alpha\rangle, |-\alpha\rangle\}$ ) (Schrödinger phase-cat).

## Analysis of the circuit stabilizing a cat-qubit (2)

Cat-qubit stored in oscillator **a**, **controller based low-Q mode b**:

$$\frac{d}{dt}\rho = -\left[g_2(\mathbf{a}^2 - \alpha^2)\mathbf{b}^\dagger - g_2((\mathbf{a}^\dagger)^2 - (\alpha^2))\mathbf{b}, \rho\right] + \kappa_b\left(\mathbf{b}\rho\mathbf{b}^\dagger - (\mathbf{b}^\dagger\mathbf{b}\rho + \rho\mathbf{b}^\dagger\mathbf{b})/2\right)$$

with  $\alpha \in \mathbb{C}$  and  $\kappa_b \gg g_2$ .

- Any density operators  $\bar{\rho} = \bar{\rho}_a \otimes |0\rangle\langle 0|_b$  is a steady-state as soon as the support of  $\bar{\rho}_a$  belongs to the two dimensional vector space spanned by the quasi-classical wave functions  $|\alpha\rangle$  and  $|\alpha^*\rangle$  ( $\text{range}(\bar{\rho}_a) \subset \text{span}\{|\alpha\rangle, |\alpha^*\rangle\}$ ) (Schrödinger cat-qubit).
- Usually  $\kappa_b \gg |g_2|$ , mode **b** relaxes rapidly to vacuum  $|0\rangle\langle 0|_b$ , can be eliminated adiabatically (singular perturbations, second order corrections) to provides the slow evolution of mode **a**:

$$\frac{d}{dt}\rho_a = \frac{4|g_2|^2}{\kappa_b} \left( (\mathbf{a}^2 - \alpha^2)\rho_a(\mathbf{a}^2 - \alpha^2)^\dagger - \frac{1}{2}((\mathbf{a}^2 - \alpha^2)^\dagger(\mathbf{a}^2 - \alpha^2)\rho_a + \rho_a(\mathbf{a}^2 - \alpha^2)^\dagger(\mathbf{a}^2 - \alpha^2)) \right).$$

Exponential convergence toward the code space  $\text{span}\{|\alpha\rangle, |\alpha^*\rangle\}$  based on the following exponential Lyapunov function<sup>16</sup>

$$V(\rho_a) = \text{Tr} \left( (\mathbf{a}^2 - \alpha^2)^\dagger (\mathbf{a}^2 - \alpha^2) \rho_a \right), \quad \frac{d}{dt} V \leq -\frac{8|g_2|^2}{\kappa_b} V.$$

- Photon-number parity  $\text{Tr} \left( e^{i\pi\mathbf{a}^\dagger\mathbf{a}} \rho \right)$  is invariant since  $[\mathbf{a}^2, e^{i\pi\mathbf{a}^\dagger\mathbf{a}}] \equiv 0$ .

<sup>16</sup> For a mathematical proof of convergence analysis in an adapted Banach space, see : R. Azouit, A. Sarlette, PR: Well-posedness and convergence of the Lindblad master equation for a quantum harmonic oscillator with multi-photon drive and damping. 2016, ESAIM: COCV, Vol. 22, No. 4, p. 1353-1369.

Take  $|\alpha| \gg 1$  (with  $|\alpha| > 3$  one has  $\langle \alpha | -\alpha \rangle \leq e^{-18}$ ) and the following logical state

$$|0\rangle_L \approx |\alpha\rangle, \quad |1\rangle_L \approx |-\alpha\rangle$$

Even and odd cats read

$$|+\rangle_L = \frac{1}{\sqrt{2}}(|0\rangle_L + |1\rangle_L) \quad \text{and} \quad |-\rangle_L = \frac{1}{\sqrt{2}}(|0\rangle_L - |1\rangle_L).$$

Dynamic governed by the following Lindblad master equation

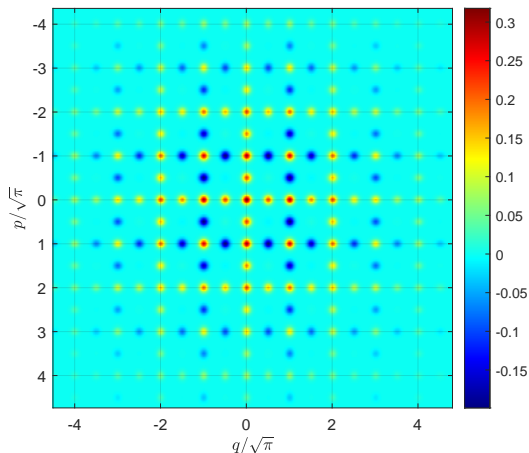
$$\frac{d}{dt}\rho = \mathbb{D}_{L_0}(\rho) + \kappa_1 \mathbb{D}_{L_1}(\rho)$$

with  $\mathbb{D}_L(\rho) \triangleq L\rho L^\dagger - \frac{1}{2}(L^\dagger L\rho + \rho L^\dagger L)$ , two-photon pumping  $L_0 = \mathbf{a}^2 - \alpha^2$  and the main error channel  $L_1 = \mathbf{a}$  corresponding to photon losses.

Matlab script `CatQubit.m`:

- $\alpha^2 = 25/2, k_1 = 1/10$ .
- truncation to  $n_{\max} \approx \alpha^2 + 15\alpha$  of the Fock basis
- discretization time  $dt = 10^{-3}/\alpha^2$
- numerical integration between  $t = 0$  to  $t = 10/\alpha^2$  starting from vacuum,  $|+\rangle_L$  and  $|0\rangle_L$ .

# Wigner function of a GKP grid-state



Magic logical-qubit state encoded in a GKP grid-state with finite energy:

$$\psi(q) \propto e^{-\epsilon q^2} \left( \sum_k \cos\left(\frac{\pi}{8}\right) e^{-\frac{(q-2k\sqrt{\pi})^2}{\epsilon}} + \sin\left(\frac{\pi}{8}\right) e^{-\frac{(q-(2k+1)\sqrt{\pi})^2}{\epsilon}} \right) \text{ with } 0 < \epsilon \ll 1.$$

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# Conclusion of these lectures

## Topics partially covered:

- Models of open quantum systems based on density operators, Kraus maps and Stochastic Master Equation (SME).
- Positivity preserving numerical schemes for simulation with classical computers.
- Two key quantum systems: qubit (two-level system) and harmonic oscillator (cavity mode).
- Two approximation methods, averaging (RWA) and singular perturbations (adiabatic elimination), for open-loop control and closed-loop stabilization with a quantum controller.
- Convergence analysis based on Lyapunov techniques and super-martingales.

## Absent topics;

- Open-loop control: adiabatic control, optimal control, ensemble control and parametric robustness
- Stabilisation with a classical controller: measurement based feedback, quantum error correction.
- State and parameter estimation: quantum filtering and tomography.
- ...